# On the Lower Semicontinuity of the Set-Valued Metric Projection 

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## 1. Introduction

Let $X$ be a real normed linear space and $V$ a proximinal subset of $X$. To each element $f$ in $X$ we associate the set

$$
P_{V}(f):=\left\{v_{0} \in V:\left\|f-v_{0}\right\|=\inf _{v \in V} f-v_{n}\right\}
$$

which is called the set of best approximations for $f$ by elements of $V$. Thus we obtain a set-valued mapping $P_{V}$, which carries the normed linear space $X$ into the set of the closed nonvoid subsets of $V$. This set-valued mapping is called the metric projection associated with $V$.

For set-valued mappings concepts of continuity are defined as follows (cf. Hahn [5]):

Definition 1. (a) The metric projection $P_{V}$ is called upper semicontinuous (usc) if the set

$$
\left\{f \in X: P_{V}(f) \cap K \neq \varnothing\right\}
$$

is closed whenever $K$ is a closed subset of $V$.
(b) The metric projection is called lower semicontinuous (lsc) if the set

$$
\left\{f \in X: P_{V}(f) \cap U \not \subset \varnothing\right\}
$$

is open whenever $U$ is an open subset of $V$. (The topology on $V$ is understood to be induced by the norm-topology of $X$ ).

The metric projection $P_{V}$ is usc or Isc only for restricted classes of subsets $V$. Singer [8], for example, has proved that the metric projection associated with an approximatively compact subset $V$ of a normed linear space is usc. Hence, in particular, $P_{V}$ is usc whenever $V$ is a linear subspace of finite dimension. But even if $V$ is a linear subspace of finite dimension, $P_{V}$ may fail to be Isc, as Blatter, Morris, and Wulbert [2] have shown.

In this paper, we first prove a general criterion which is sufficient for the lower semicontinuity of the metric projection associated with certain subspaces of a normed linear space. As a consequence of this criterion, we obtain a result of Brosowski et al. [4]. Further we apply our criterion to derive a sufficient condition for the lower semicontinuity of the metric projection associated with certain linear subspaces of $C_{0}(T, X)$, where $T$ is a locally compact Hausdorff-space, $X$ is a strictly convex normed linear space, and $C_{0}(T, X)$ is the set of all continuous functions $f: T \rightarrow X$ which vanish at infinity, provided with the norm $\|f\|:=\max _{t \in T}\|f(t)\|_{X}$.

We shall show that in $C_{01}(T, X)$ the criterion thus obtained is also necessary for the lower semicontinuity of $P_{V}$. This generalizes the results of Blatter [1], Blatter, Morris, and Wulbert [2], and Brosowski et al. [3].

Furthermore, we apply our general sufficient criterion to prove the sufficiency of a criterion stated by Lazar, Wulbert, and Morris [6] for the lower semicontinuity of the metric projection associated with finitedimensional linear subspaces of $L_{1}(T, \Omega, \mu)$, where $(T, \Omega, \mu)$ is a $\sigma$-finite measure space.
2. A Sufficient Condition For the Lower Semicontinuity of $P_{V}$

We first state some necessary definitions. For $X$ a normed linear space, we define

$$
S_{X}:=\{x \in X:\|x\| \leqslant 1\}
$$

and

$$
\mathscr{E}_{X}:=\operatorname{Ep}\left(S_{X}\right)
$$

where $\operatorname{Ep}(A)$ denotes the set of extreme points of a set $A$. For $f \in X$, we set

$$
\Sigma_{f}:=\left\{x^{\prime} \in S_{X^{\prime}}: x^{\prime}(f)=\|f\|\right\}
$$

and

$$
\mathscr{E}_{f}:=\left\{x^{\prime} \in \mathscr{E}_{X^{\prime}}: x^{\prime}(f)=\|f\|\right\}
$$

As is well known, $\mathscr{E}_{f}=\Sigma_{f} \cap \mathscr{E}_{X^{\prime}}$. We use the terms $\sigma$-topology and $\sigma_{\mathrm{En}^{-}}$ topology to denote the restrictions of the weak topology $\sigma\left(X^{\prime}, X\right)$ on the sets $S_{X^{\prime}}$ and $\delta_{X^{\prime}}$, respectively. For $V$ a proximinal linear subspace of $X$ and $f$ in $X$ with $0 \in P_{V}(f)$, we define the set

$$
\mathfrak{N}_{t, v}:=\bigcap_{t \in P_{V^{\prime}(t)}}\left\{x^{\prime} \in \mathscr{O}_{x^{\prime}}: x^{\prime}(t)-0\right.
$$

The subscript $V$ will be omitted if it is understood from the context. Finally, we define

$$
E(f ; V):=-\inf _{r \in V} f-v:
$$

Now we prove the following.
Lemma 2. Let $A$ be a subset of $\mathcal{O}_{\mathrm{x}}$ and $f$ an element in $X$. Then the inequalir!'

$$
\sup _{x^{\prime} \in A} x^{\prime}(f) \therefore f
$$

holds if and only if there exists a $\sigma\left(X^{\prime}, X\right)$-open convex subset $U$ of $X^{\prime}$ such that

$$
\theta_{x} \backslash A \supset U \cap \delta_{x} \supset i_{x}
$$

Proof. Let $A$ be a subset of $\epsilon_{X^{\prime}}$. Whenever

$$
s:=\sup _{x^{\prime} \in A} x^{\prime}(f) \quad f^{\prime}
$$

then there is an $\epsilon=0$ so that $s<\| f$. For the $\sigma\left(X^{\prime}\right.$. $X$ )-open convex set

$$
U:=\left\{x^{\prime} \in X^{\prime}: x^{\prime}(f) \quad f: \in\right.
$$

we have $A \cap U=\varnothing$, and hence $A \cap\left(U \cap \delta_{x}\right) \cdots$ Thus we obtain

$$
\mathscr{E}_{x^{\prime}, A \supset U \cap \dot{r}_{1} \supset f_{1} .}
$$

To prove the inverse implication, we assume that $U$ is a o $\left(X^{\prime}, X\right)$-open convex subset of $X^{\prime}$ such that

$$
\delta_{X} \backslash A \supset U \cap \delta_{X} \supset \delta_{j}
$$

Then

The Krein-Milman theorem yields $\Sigma_{f}=\overline{\operatorname{con} \mathscr{E}_{f}}$. Since $U$ is convex, and contains $\mathscr{E}_{f}$, there follows $U \supset$ con $\mathscr{\varepsilon}_{f}$. We show that $U \supset \Sigma_{f}$. In fact, suppose that there is an element $x_{0}{ }^{\prime}$ in $\Sigma_{f}$ which is not in $U$. Then $x_{0}{ }^{\prime}$ is in the boundary of $U$, and, since $U$ is open and convex, there exists an element $g \in X$ such that $x_{0}{ }^{\prime}(g)=\inf _{g^{\prime} \in U} y^{\prime}(g)$. Define

$$
H:=\left\{x^{\prime} \in X^{\prime}: x^{\prime}(g)=x_{0}^{\prime}(g)\right\}
$$

Since $U$ is open, $H \cap U=\varnothing$. Using $\Sigma_{f} \subset \bar{U}$ we obtain

$$
x_{0}^{\prime}(g)=\inf _{y^{\prime} \in \Sigma_{j}} y^{\prime}(g),
$$

whence $H \cap \Sigma_{f}$ is an extremal subset of $\Sigma_{f}$. Therefore $H \cap \Sigma_{f}$ contains an extreme point $x_{1}{ }^{\prime}$ of $\Sigma_{f}$. In view of $\mathscr{E}_{f} \subset U$ we have $x_{1}{ }^{\prime} \in H \cap U$, which contradicts $H \cap U=\square$. Thus we have $U \supset \Sigma_{f}$ and finally, since $S_{X} \backslash U$ is compact,

$$
\sup _{x^{\prime} \in S_{X^{\prime} \backslash U}} x^{\prime}(f)<\| f!
$$

This completes the proof.
We are now ready to prove the following.
Theorem 3. Let $V$ be a proximinal linear subspace of a normed linear space $X$ with the properties:
(1) for each $f \in X, \operatorname{dim} P_{V}(f)<\infty$,
(2) the metric projection $P_{V}$ is usc.

Whenever for each element $f$ in $X$ with $0 \in P_{v}(f)$ there exists a $\sigma\left(X^{*}, X\right)$-open convex subset $U$ of $X^{\prime}$ such that

$$
\mathfrak{M}_{f} \supset U \cap \mathscr{E}_{X^{\prime}} \supset \bigcap_{v \in P_{V^{\prime}}(f)} \mathscr{\delta}_{f-v}
$$

then $P_{v}$ is $l s c$.
Procf. We assume that there exists a point $f$ in $X$ so that $P_{V}$ is not lsc in $f$. Then there exists a sequence $\left\{f_{n}\right\}$ of elements $f_{n}$ in $X$, an element $v_{0}$ in $P_{v}(f)$ and a neighborhood $U_{0}$ of $v_{0}$ such that $\left\{f_{n}\right\}$ converges to $f$ and

$$
P_{V}\left(f_{n}\right) \cap U_{0}=\varnothing
$$

for each $n$. The set $P_{V}(f)$ is convex and, since $P_{V}$ is usc, consists of more than one point. We may assume without loss of generality that $v_{0}$ is a relative interior point of $P_{V}(f)$. Replacing $f$ by $f-v_{0}$ if necessary, we may assume that $v_{0}=0$.

Then it follows that

$$
\mathbf{9}_{f} \supset \bigcap_{r \in P_{V}(f)} \delta_{t}, \delta_{t}
$$

For each $g \in X$ the set $P_{V}(g)$ is closed, bounded and finite-dimensional, and hence compact. Since $P_{V}$ is usc, the set

$$
P_{V}(f) \cup \bigcup_{n \in \mathbb{N}} P_{V}\left(f_{n}\right)
$$

is compact (cf. Michael [7]). Consequently there is a subsequence of $\left\{f_{n}\right\}$ (which we denote again by $\left\{f_{n}\right\}$ ), so that there exist elements $v_{n}$ in $P_{V}\left(f_{n}\right)$ in such a way that the sequence $\left\{r_{n}\right\}$ converges to an element $v^{\prime}$ in $V$. Then $v^{\prime} \in P_{V}(f)$, and furthermore $v^{\prime} \neq 0$ since $P_{v}\left(f_{n}\right) \cap U_{0}=$ for all $n \in \mathbb{N}$.

Following Brosowski et al. [4], we can now construct a sequence $\left\{u_{n}\right\}$ of elements $u_{n}$ in $X$ with the following properties:
(a) the sequence $\left\{u_{n}\right\}$ converges to $l^{\prime}$ :
(b) for each $n \in \mathbb{N}$ there holds

$$
\left|f-u_{n}\right|=E(f ; V):
$$

(c) there exists an integer $n_{0} \in \mathbb{N}$ so that

$$
\left|f-u_{n}+v^{\prime}\right|:>E(f: V) \quad \text { for all } n \because n_{0}
$$

Such a sequence may be defined explicitly by

$$
u_{n}:=f-\left(E(f ; V) / E\left(f_{n} ; V\right)\right)\left(f_{n}-\imath_{n}\right)
$$

Obviously this sequence has properties (a) and (b). To show that $\left\{u_{n}\right\}$ also shares property (c), we note that $\left\|f-u_{n}+r^{\prime}\right\| \geqslant E(f: V)$, since

$$
\begin{equation*}
f-u_{n}+v^{\prime}=\left(E(f ; V) / E\left(f_{n} ; V\right)\right)\left(f_{n}-\left(c_{n}-\left(E\left(f_{n}: V\right) / E(f ; V)\right) v^{\prime}\right)\right) . \tag{1}
\end{equation*}
$$

If there is some subsequence of $\left\{u_{n}\right\}$ (again denoted by $\left\{u_{n}\right\}$ ) such that $\left\|f-u_{n}-r^{\prime}\right\|=E(f ; V)$, then, by (1), the element

$$
\bar{v}_{n}:=c_{n}-\frac{E\left(f_{n} ; V\right)}{E(f ; V)} r^{\prime}
$$

is in $P_{\nu^{\prime}}\left(f_{n}\right)$, and the sequence $\left\{\bar{v}_{n}\right\}$ converges to the zero element in $V$. This is impossible since $P_{V}\left(f_{n}\right) \cap U_{0}=\varnothing$ for each $n$. Hence (c) is proved.

For $n=n_{0}$ and $x^{\prime} \in \mathscr{E}_{f-u_{n}+v^{\prime}}$ we have

$$
\begin{aligned}
& E(f ; V)<\| f-u_{n}+v^{\prime} \\
& \quad=x^{\prime}\left(f-u_{n}+v^{\prime}\right)=x^{\prime}\left(f-u_{n}\right)+x^{\prime}\left(c^{\prime}\right) \\
& \quad \leqslant E(f ; V)+x^{\prime}\left(v^{\prime}\right) .
\end{aligned}
$$

which yields $x^{\prime}\left(v^{\prime}\right)>0$. Hence we obtain

$$
\begin{equation*}
\mathfrak{M}_{f} \cap \mathscr{I}_{f-u_{n}+u^{\prime}}=6 \quad \text { for } \quad n>n_{0} \tag{2}
\end{equation*}
$$

On the other hand, by hypothesis, there exists a $\sigma\left(X^{\prime}, X\right)$-open convex subset $U$ of $X^{\prime}$ so that

$$
\mathfrak{m}_{j} \supset \cup \cap \mathscr{f}_{x^{\prime}} \supset \mathscr{f}_{f}
$$

and, by Lemma 2,

$$
\sup _{x^{\prime} \in \delta_{X^{\prime}} \backslash U} x^{\prime}(f)<\quad f \|=E(f ; V)
$$

Hence there exists a real number $\epsilon>0$ such that

$$
x^{\prime}(f) \leq E(f ; V)-\epsilon
$$

for each $x^{\prime} \in \mathscr{E}_{X^{\prime}} \backslash U$. The sequence $\left\{u_{n}\right\}$ converges to $v^{\prime}$. Therefore we have : $u_{n}-v^{\prime} \|<\epsilon$ for sufficiently large $n$, and consequently

$$
x^{\prime}\left(f-u_{n}-v^{\prime}\right)<E(f ; V)
$$

for all $x^{\prime}$ in $\mathscr{E}_{X^{\prime}} \backslash U$, in particular for $x^{\prime}$ in $\mathscr{E}_{X^{\prime}} \backslash \boldsymbol{N}_{f}$. Thus we obtain for sufficiently large $n$ the inclusion $\boldsymbol{M}_{j} \supset \mathscr{\varepsilon}_{f-u_{n}+v^{\prime}}$ which contradicts (2). The theorem is thus proved.

A consequence of Theorem 3 is the following result of Brosowski et al. [4].
Theorem 4. Let $V$ be a proximinal linear subspace of a normed linear space $X$ with the properties (1), (2) of Theorem 3 and the following additional property:

$$
\begin{equation*}
\text { The set } \delta_{x^{\prime}} \text { is } \sigma \text {-closed. } \tag{3}
\end{equation*}
$$

Whenever for each element $f$ in $X$ with $0 \in P_{V}(f)$ there exists a $\sigma$-open subset $A$ of $S_{X^{\prime}}$ such that

$$
\mathfrak{\Re}_{j} \supset A \cap \mathscr{E}_{X^{\prime}} \supset \bigcap_{v \in P_{V}(f)} \mathscr{E}_{f-v}
$$

then the metric projection $P_{V}$ is 1 sc .
Proof. In view of property (3), the set $\mathscr{E}_{X^{\prime}}$ is $\sigma$-compact. Hence we obtain

$$
\sup _{x^{\prime} \in \delta_{X^{\prime} \backslash A} \backslash} x^{\prime}(f)<\|f\|,
$$

and, using the hypothesis,

$$
\sup _{x^{\prime} \in \mathscr{O}^{\mathscr{E}} X^{\prime}\left(\omega_{f},\right.} x(f) \cdots f
$$

Thus, by Lemma 2, there is a $\sigma\left(X^{\prime}, X\right)$-open convex subset $U$ of $X^{\prime}$ such that $\boldsymbol{i}_{j} \supset U \cap \dot{\varepsilon}_{X} \supset \dot{i}_{j}$, and Theorem 3 yields the lower semicontinuity of $P_{F^{\prime}}$.

## 3. Applications in Some Special Spaces

Let $T$ be a locally compact Hausdorff space, and $X$ a strictly convex real normed linear space. We denote by $C_{n}(T, X)$ the set of continuous functions $f: T \rightarrow X$ vanishing at infinity, that is. a continuous function $f$ is in $C_{0}(T, X)$ if and only if, for each $\epsilon>0$, the set

$$
\{t \in T: f(t): \in ;
$$

is compact. If addition and multiplication with scalars are defined for elements in $C_{0}(T, X)$ in the same way as for vector-valued functions, and the norm

$$
\left.f \mid:=\max _{t=T} f(t)\right)_{x}
$$

is introduced, then $C_{0}(T, X)$ is a normed linear space. Whenever it is necessary to distinguish between the norms in $C_{0}(T, X)$ and $X$ we denote the latter by $\|\cdot\|_{X}$.

For $V$ a proximinal subspace of $C_{8}(T, X) . f$ an element in $C_{0}(T, X)$ with $0 \in P_{V}(f)$, and $\tau_{0}$ an element in $P_{V}(f)$, we define

$$
N_{t, 1}:=\bigcap_{r \in P_{i},(1)}\{t=7: c(t)=0\}
$$

and

$$
M_{f-r_{0}}:=\left\{t \in T: f(t)-l_{0}(t)_{x}=f-v_{0}\right\}
$$

The subscript $V$ will be omitted if it is understood from the context.
Now we prove the following.
Lemma 5. Let $V$ be a proximinal linear subspace of $C_{0}(T, X)$, where $X$ is strictly convex. Then

$$
N_{f} \supset \bigcap_{v \in P_{P^{*}+}+j} M_{f \ldots r}
$$

for each element f in $C_{0}(T, X)$ with 0 in $P_{r}(f)$.

Proof. Let $t$ be in $\bigcap_{v \in P_{V}(f)} M_{f-\varepsilon}$. Since $0 \in P_{V}(f)$, for each $r$ in $P_{V}(f)$ the element $\frac{1}{2} v$ is also in $P_{r}(f)$. Hence

$$
\left.\left\|f(t)-\frac{1}{2} t(t)\right\|=\frac{1}{2}\|f(t)\|+\frac{1}{2} \| f(t)-l(t) \right\rvert\, .
$$

In view of the strict convexity of $X$, there is a positive real number $\mu$ such that

$$
f(t)=\mu(f(t)-\imath(t)) .
$$

Using $\|f(t)\|=\|f(t)-v(t)\|$, we obtain $\mu=1$ and finally $r(t)=0$, whence $t \in N_{f}$.

Now we give a sufficient criterion for the lower semicontinuity of $P_{V}$ in $C_{0}(T, X)$.

Theorem 6. Let $V$ be a proximinal linear subspace of the space $Z:=C_{0}(T, X)$, where $T$ is a locally compact Hausdorff space, and $X$ is a strictly convex space. Assume that the following requirements hold:
(1) for each $f$ in $Z, \operatorname{dim} P_{V}(f)<\infty$;
(2) the metric projection $P_{V}$ is usc.

Whenever for each $f$ in $Z$ with $0 \in P_{V}(f)$ the set $N_{f}$ is open then the metric projection is lsc.

Proof. The set $N_{f}$ is defined to be the intersection of the closed sets $\{t \in T: v(t)=0\}, v \in P_{V}(f)$, hence it is closed. Since $N_{f}$ is also open by hypothesis, the function $g$ defined by

$$
g(t):=\left\{\begin{array}{lll}
f(t) & \text { for } & t \text { in } N_{f}, \\
10 & \text { for } & t \text { in } T \backslash N_{f},
\end{array}\right.
$$

is in $C_{0}(T, X)$. The set

$$
U:=\left\{z^{\prime} \in Z^{\prime}: z^{\prime}(g)>0\right\}
$$

is a $\sigma\left(Z^{\prime}, Z\right)$-open and convex subset of $Z^{\prime}$.
The functionals in $\mathscr{E}_{Z^{\prime}}$ are generalized evaluation functionals $L_{x^{\prime}, t}$, that is, there exist elements $x^{\prime} \in \mathscr{E}_{X^{\prime}}$ and $t \in T$ such that

$$
L_{x^{\prime}, t}(h)=x^{\prime}(h(t)) \quad \text { for } \quad h \in C_{0}(T, X) .
$$

By definition of $U$, for each functional $L_{x^{\prime}, t} \in \mathscr{E}_{Z^{\prime}} \cap U$, the equality

$$
L_{x^{\prime}, t}(v)=x^{\prime}(v(t))=x^{\prime}(0)=0
$$

holds for all $t$ in $P_{t}(f)$, whence we conclude $\boldsymbol{M}_{f} \supset \delta_{Z^{\prime}} \cap U$. Using Lemma 5 . we obtain the inclusion

Thus the requirements of Theorem 3 are fulfilled, whence the lower semicontinuity of $P_{F}$, follows.

Remarks. Special cases of Theorem 6 have appeared in the literature. For $T$ compact and $X$ the real axis, the theorem was proved by Blatter, Morris, and Wulbert [2]. For $T$ locally compact and $X$ a pre-Hilbert space, the result was obtained by Brosowski et al. [4].

Now let $X$ be the space $L_{1}(T, \Omega, \mu)$. where $(T, \Omega, \mu)$ is a $\sigma$-finite measure space. The dual space $X^{\prime}$ is identical to $L_{\Omega}(T, \Omega, \mu)$. For $f$ a real-valued function defined on $T$, we set

$$
\begin{aligned}
\operatorname{supp}(f) & :=\{t \in T: f(t) \quad 0\} \\
Z(f) & :-\{t \in T: f(t)=0\} \\
S(f) & :=\left\{t \in T: f(t) \quad \sup _{s \in T} \mid f(s)\right\} .
\end{aligned}
$$

These sets are defined only up to sets of zero measure.
In addition. we define for each linear subspace $V$ of $X$ the orthogonal space

$$
V^{\prime}:=\left\{x^{\prime} \in X^{\prime}: x^{\prime}(v)=0 \text { for each } v \in V ;\right.
$$

Lazar, Wulbert, and Morris [6] proved the following criterion.
Theorem 7. Let $(T, \Omega, \mu)$ be a o-finite measure space, and let $V$ be an $n$-dimensional linear subspace of $L_{1}(T, \Omega, \mu)$. The metric projection $P_{V}$ is Isc if and only if there does not exist an $x^{\prime}$ in $V, x^{\prime}-0$, and $a v$ in $V$ for which
(1) $S\left(x^{\prime}\right)$ is purely atomic, and contains at most $n-1$ atoms,
(2) $Z(v)$ contains $S\left(x^{\prime}\right)$,
(3) $\operatorname{supp}(v)$ is not the union of a finite family of atoms.

We give a new proof for the sufficiency of this criterion by showing that the condition of Lazar, Wulbert, and Morris implies the condition of Theorem 3. From this, it follows in the case $X=L_{1}(T, \Omega, \mu)$ that the condition of Theorem 3 is also necessary for the lower semicontinuity of $P_{V}$.

Proof of the sufficiency of the criterion in Theorem 7. We suppose that the condition of Theorem 7 holds but that there exists an element $f \in L_{1}$ with $0 \in P_{V}(f)$ (without loss of generality we may even assume that 0 is a relative
interior point of $P_{\mathrm{V}}(f)$ ) such that $\mathrm{M}_{f}$ does not contain $U \cap \mathscr{U}_{X}$ whenever $U$ is a $\sigma\left(X^{\prime}, X\right)$-open convex subset of $X^{\prime}$ with $U \cap \mathscr{C}_{x} \cdot \supset \mathscr{G}_{f}$.

First we show that there exists an element $\dot{v}$ in $P_{V}(f)$ such that $\operatorname{supp}(\tilde{v})$ is not the union of a finite family of atoms.

To prove this, we suppose that for each $v$ in $P_{V}(f)$, the support supp $(v)$ is a union of a finite number of atoms. Then there exist atoms $A_{1}, \ldots, A_{N}$ such that

$$
\operatorname{supp}\left(c^{\prime}\right) \subset A:=A_{1} \cup \cdots \cup A_{N}
$$

for each $v$ in $P_{V}(f)$.
For every $x \in P_{V}(f)$ and every $x^{\prime} \in \delta_{j}$, we have $x^{\prime}(x)=0$. Since the functionals $x^{\prime} \in \delta_{f}$ (interpreted as functions in $L_{x}$ ) may be chosen outside supp ( $f$ ) arbitrarily retaining only the requirement $\left|x^{\prime}(t)\right|=1$, there must be $\operatorname{supp}(v) \subset \operatorname{supp}(f)$ for all $i \in P_{V}(f)$. Therefore one may assume $A \subset \operatorname{supp}(f)$.

Corresponding to the set

$$
W:=\left\{x^{\prime} \in \delta_{x^{\prime}}: x^{\prime}(t)=\operatorname{sign}(f(t)) \text { for } t \in A\right\}
$$

there exists a $\sigma\left(X^{\prime}, X\right)$-open convex subset $U$ of $X^{\prime}$ so that $W \because U \cap \mathscr{E}_{X^{\prime}}$, namely, e.g.

$$
U:=\left\{x^{\prime} \in X^{\prime}: \int_{T} x^{\prime}(t)\left(\chi_{A_{1}}(t) \cdot f(t)\right) d \mu=0 \text { for } v=1, \ldots, N_{\}}^{\prime}\right.
$$

where $\chi_{A_{v}}$ denotes the characteristic function of the set $A_{v}$. In addition, we have

$$
\boldsymbol{M}_{f} \supset W=U \cap \delta_{x^{\prime}} \supset \delta_{t}
$$

Since such a relation was excluded by the choice of $f$, we have proved our assertion that there exists some element $\tilde{w}$ in $P_{V}(f)$ such that $\operatorname{supp}(\dot{z})$ is not the union of a finite number of atoms.

Now let

$$
\begin{aligned}
Y^{\prime}:=\left\{x^{\prime}\right. & \in S_{X^{\prime}}: x^{\prime}(c)=0 \text { for all } v \in V, \\
x^{\prime}(t) & =\operatorname{sign}(f(t)) \text { for } t \in \operatorname{supp}(f)\},
\end{aligned}
$$

then $Y^{\prime}$ is convex and $\sigma$-compact. By the well-known theorem of characterization of best approximations, there exists a functional $x^{\prime} \in \Sigma_{f}$ such that $x^{\prime}(v)=0$ for all $r$ in $V$. Since this $x^{\prime}$ is in $Y^{\prime}$, the set $Y^{\prime}$ is nonvoid. Hence there exists some extreme point $y^{\prime}$ of $Y^{\prime}$. By construction, we have $\mid y^{\prime}(t)^{\prime}=1$ for $t \in \operatorname{supp}(f)$. Since $\operatorname{supp}(\tilde{v}) \subset \operatorname{supp}(f)$ it follows that $Z(\tilde{v}) \supset S\left(y^{\prime}\right)$.

Now we show that $S\left(y^{\prime}\right)$ is purely atomic and consists of at most $n-1$ atoms. Let $t^{1}, t^{2}, \ldots . t^{n}$ be a basis for $V$ with $t^{1}=\widetilde{\imath}$.

First we exclude that $S\left(y^{\prime}\right)$ contains a nonatomic part. In fact, let $B \subset S\left(y^{\prime}\right)$ be a nonatomic subset of $S\left(y^{\prime}\right)$ with $\mu(B)>0$. Then there exists $\epsilon>0$ so that

$$
B_{1}:=\left\{t \in B: y^{\prime}(t) \cdot 1-\epsilon\right\}
$$

has $\mu\left(B_{1}\right) \div 0$. Then there exists a function $z^{\prime} \in S_{X^{\prime}}, z^{\prime} 0$, such that $\operatorname{supp}\left(z^{\prime}\right) \subset B_{1}$ and $\int_{B_{1}} z^{\prime}(t) v^{i}(t) d \mu=0$ for $i=1, \ldots n$. For either sign, $y^{\prime} \pm \epsilon z^{\prime}$ is in $Y^{\prime}$. This contradicts the fact that $y^{\prime}$ is an extreme point of $Y^{\prime}$.

Now let us suppose $S\left(y^{\prime}\right) \supset B=B_{1} \cup \cdots \cup B_{n}$, where $B_{v}$ are atoms. It follows that $\epsilon:=1-\operatorname{ess}^{-s u p} p_{t \in B}\left|y^{\prime}(t)\right|>0$. Let $v_{t}^{\prime}$ be the value of $v^{i}$ on the atom $B_{v}$. The system of equalities

$$
\begin{equation*}
\sum_{v=1}^{n} \alpha_{v} i_{\nu}{ }^{i} \mu\left(B_{v}\right)=0, \quad i=2, \ldots, n, \tag{4}
\end{equation*}
$$

has a nonzero solution $\alpha_{1}{ }^{\prime \prime}, \ldots . x_{n}{ }^{\prime \prime}$ with $; \alpha_{x^{\prime}}{ }^{0} \mid=1$ for all $i$. Hence for either sign the function $z^{\prime}$, defined by

$$
z^{\prime}(t):= \begin{cases}y^{\prime}(t) \pm \epsilon x_{v}^{0} & \text { for } t \in B_{v} \\ y^{\prime}(t) & \text { for } t \notin B\end{cases}
$$

is in $Y^{\prime}$. This is impossible since $y^{\prime}$ is an extreme point of $Y^{\prime}$. Therefore $S\left(y^{\prime}\right)$ contains at most $n-1$ atoms.

So far, we have constructed elements $\tilde{v} \in V$ and $y^{\prime} \in Y^{\prime} C V$ which fulfil the requirements (1), (2), and (3) of Theorem 7. But the condition of Theorem 7 states that such elements do not exist. Hence our assumption is not correct. Thus we have proved, that the condition of Lazar, Wulbert, and Morris implies the condition of Theorem 3. Since the latter is sufficient for the lower semicontinuity of $P_{V}$ the sufficiency part of Theorem 7 is proved.

## 4. The Necessity of the Criterion in the Space $C_{1}(T, X)$

In this paragraph, we show that the sufficient condition of Theorem 6 is also necessary if the space under consideration is $C_{0}(T, X)$. where $X$ is strictly convex. First we prove the following lemma.

Lemma 8. Let $V$ be a linear subspace of $C_{0}(T, X)$, and let $f$ and $g$ be elements in $C_{0}(T, X)$ with
(a) $\|f\|=\|g\|$;
(b) $0 \in P_{V}(f)$ and $0 \in P_{V}(g)$ :
(c) there is a neighbourhood $U$ of $M_{f}$ such that $f(t)-g(t)$ for $t \in U$.

Then $P_{v}(g)$ is contained in span $P_{v}(f)$, i.e., in the linear subspace of $V$ which is spanned by $P_{\mathrm{r}}(f)$.

Proof. Given an element $r=0$ in $P_{V}(g)$. let $\lambda$ be the positive number

$$
\lambda:-\min \left(1,\left(1 f, \cdots E^{*}\right) / t i\right)
$$

with

$$
E^{*}:=\sup _{t \in T \backslash U} f(t) x \cdot f \mid .
$$

By virtue of hypothesis (b), the element $c_{1}:-\lambda_{c}$ is also in $P_{f}(g)$. We have for $t$ in $l$

$$
f(t)-c_{1}(t)=g(t)-l_{1}(t) \quad g=!f
$$

and for $t \in T \backslash$

$$
f(t)-c_{1}(t)<f(t)-c_{1}(t)=E^{*}-\left(f-E^{*}\right)=!f
$$

Hence the element $\tau_{1}$ is a best approximation for $f$, and $r=(1 / \lambda) r_{1}$ is in $\operatorname{span} P_{V}(f)$.

We are now in position to prove the main result of this paragraph.
THEOREM 9. Let $T$ be a locally compact Hausdorff space, $X$ a strictly convex normed linear space, and let $V$ be a proximinal linear subspace of $C_{0}(T, X)$ such that dim $P_{V}(f)<\infty$ for all $f$ in $C_{0}(T, X)$. Whenever the metric projection $P_{V}$ is $l s c$, then, for each $f$ in $C_{0}(T, X)$ with 0 in $P_{V}(f)$, the set

$$
N_{f}:=\bigcap_{v \in P_{v}(f)}\{t \in T: r(f)=0\}
$$

is open.
Proof. We suppose the theorem is false, that is, there exists an element $f_{1}$ in $C_{0}(T, X)$ with $0 \in P_{V}\left(f_{1}\right)$ such that $N_{f_{1}}$ is not open. Then $f_{1}$ is not in $V$, since otherwise $P_{\mathrm{V}}\left(f_{1}\right)=\left\{f_{1}\right\}$ and $N_{f_{1}}=T$ would be open. Without loss of generality we may assume $\left\|f_{1}\right\|=1$.

Now let $v_{1}, \ldots, v_{k}$ be linear independent elements in $P_{V}\left(f_{1}\right)$ which span the linear subspace $V_{1}:==\operatorname{span} P_{V}\left(f_{1}\right)$ of $V^{\prime}$.

Since $N_{f_{1}}$ is not open, there is a point $t_{0}$ in $N_{f_{1}}$ with the property:
(E) every neighborhood $U$ of $t_{0}$ contains some point $t_{U}$ such that $\tau_{n}\left(t_{U}\right) \neq 0$ for at least one $\kappa \in\{1, \ldots, k\}$.

Now we construct a function $f$ as follows. In the case $t_{0}$ is in $M_{f_{1}}$, we define $f:-f_{1}$. If $t_{0}$ is not in $M_{f_{1}}$, then we first choose an element $r$ in $X$ such that
$\| r:=\mathrm{I}$ and $r-f_{1}\left(f_{0}\right)_{x}: 1-f_{1}\left(t_{0}\right) \|_{x}$. A possible choice is, for instance.

$$
r \cdots f_{1}\left(t_{0}\right) / / f_{1}\left(t_{0}\right)_{X}
$$

in the case $f_{1}\left(t_{0}\right) \neq 0$. If $f_{1}\left(t_{0}\right)=0$. each $r$ with $r-1$ will do. Since $t_{0}$ is not in the closed set $M_{f_{1}}$. there is a compact neighborhood $U$ of $t_{0}$ such that $M_{f_{1}} \cap U=\pi$. From $t_{19} \in N_{f_{1}}$ there follows for $\kappa \quad 1, \ldots k$

$$
r_{n}\left(t_{0}\right)=0
$$

and

$$
f_{1}\left(f_{0}\right)-r_{k}\left(t_{0}\right)-f_{1}\left(t_{0}\right)<1
$$

By reducing $U$, if necessary, we can ensure that, for all $t \in U$.

$$
f_{1}(t)-r_{n}(t)<1, \quad \kappa=1, \ldots, k
$$

and

$$
r-f_{1}(t)=0
$$

There exists a continuous function $\rho_{1}(t)$ such that $0 \quad \rho_{1}(t) \leqslant 1$ for all $t \in T, \rho_{1}\left(t_{0}\right)=1$, and $\rho_{1}(t)=0$ for $t \notin U$. In addition, we put

$$
\rho_{2}(t):=\min _{1 \sim \kappa}\left(\left(1-f_{1}(t)-r_{\kappa}(t) \eta\right) r-f_{1}(t)\right)
$$

and

$$
\rho_{3}(t):=\min \left(\rho_{1}(t), \max \left(0, \rho_{2}(t)\right)\right)
$$

We complete the definition of $\rho_{2}$ and $\rho_{3}$ by setting $\rho_{2}(t)=\rho_{3}(t)=0$ for those $t$ which have $r-f_{1}(t)=0$, and thus obtain a continuous function $\rho_{3}$ with $0 \leqslant \rho_{3}(t) \leqslant 1$ for all $t \in T, \rho_{3}\left(t_{0}\right)=1$, and $\rho_{3}(t)=0$ for $t \leqslant T \backslash U$. Now we define the function $f$ by

$$
f(t):=\left(1-\rho_{3}(t)\right) f_{1}(t)+\rho_{3}(t) \cdot r
$$

This function has the property that $f(t) \quad f_{1}(t)$ for all $t$ in $T U$, and $f\left(t_{0}\right)=r$, whence $\left\|f\left(t_{0}\right)\right\|=1$ and $t_{0} \in M_{t}$. Since $T \backslash U$ is, by construction, an open set containing $M_{f_{1}}$, it follows that $M_{f_{1}} \subset M_{f}, 0 \in P_{V}(f)$, and finally from Lemma $8, P_{V}(f) \subset V_{1}$. For each $t$ in $T$ and each $\kappa=1, \ldots, k$ we have

$$
\begin{aligned}
f(t)-v_{k}(t) \|^{\prime} & =\| f_{1}(t)-v_{k}(t)-\rho_{3}(t)\left(r-f_{1}(t)\right) \\
& \leqslant \| f_{1}(t)-v_{n}(t)\left|+\rho_{3}(t)\right| r \cdots f_{1}(t) \\
& \leqslant f_{1}(t)-v_{k}(t)\left\|+\max \left(0, \rho_{2}(t)\right) \mid r-f_{1}(t)\right\| \leqslant 1 .
\end{aligned}
$$

Hence all $r_{1} \ldots . v_{h}$ are in $P_{V}(f)$ and, since 0 is also in $P_{V}(f)$, the element

$$
r_{0}:=\left(c_{1}+\cdots+v_{k}\right) /(k+1)
$$

is a relative interior point of $P_{V}(f)$. Then 0 is a relative interior point of $P_{V}(g)$ where $g:=f-v_{0}$.

For each $t$ in $T$, we have

$$
\begin{aligned}
g(t) & =f(t)-v_{0}(t) \\
& =\frac{1}{k-1} f(t)+\sum_{k=1}^{k}\left(f(t)-v_{n}(t)\right) \\
& \leqslant \frac{1}{k-1}, \| f(t)\left|-\sum_{k=1}^{k}\right| f(t)-v_{n}(t) \mid=1
\end{aligned}
$$

with equality if and only if $v_{n}(t)=0$ for all $\kappa=1, \ldots, k$, that is $t \in N_{/}$. Hence there follows

$$
M_{g} \subset N_{y}=N_{f}
$$

Because $t_{0}$ is not an interior point of $N_{g}$, there is a net ( $\left.t_{\lambda}: \lambda \in A\right)$ of points $t_{\lambda}$ in $T$ such that $\left(t_{\lambda}\right)$ converges to $t_{0}$ and, for each $\lambda, v_{k}\left(t_{\lambda}\right)=0$ at least for one $\kappa$. Then there exists an index $\kappa_{0}$ and a subnet $\left(t_{\lambda}: \lambda \in A_{1}\right)$ such that $v_{\kappa_{0}}\left(t_{\lambda}\right) \neq 0$ for all $t_{\lambda}$ with $\lambda \in \Lambda_{1}$. We may assume $\kappa_{0}=1$.

Now we consider two cases.
First case. There is a subnet $\left(t_{\lambda}: \lambda \in \Lambda_{2}\right)$ of ( $t_{\lambda}: \lambda \in \Lambda_{1}$ ) such that for every $\lambda \in A_{2}$ there exists some functional $x_{\lambda}{ }^{\prime} \in \mathscr{E}_{g\left(t_{0}\right)}$ with $x_{\lambda}{ }^{\prime}\left(t_{1}\left(t_{\lambda}\right)\right) \neq 0$. By passing once more to a subnet ( $t_{\lambda}: \lambda \in \Lambda_{3}$ ), we can ensure that there exist signs $\epsilon_{\kappa} \in\{-1,+1\}$ such that the inequalities

$$
\epsilon_{1} x_{\lambda}^{\prime}\left(r_{1}\left(t_{\lambda}\right)\right)<0
$$

and

$$
\epsilon_{k} x_{\lambda}^{\prime}\left(v_{k}\left(t_{\lambda}\right)\right) \leqslant 0, \quad \text { for } \quad \kappa=2, \ldots, k,
$$

hold.
For each $\delta>0$, the set

$$
A_{\delta}:=\left\{t \in T:\left\|g\left(t_{0}\right)-g(t)\right\|<\delta\right\}
$$

is a neighborhood of $t_{0}$. Hence there exists $\lambda \in \Lambda_{3}$ such that $t_{\lambda} \in \boldsymbol{A}_{\hat{\partial}}$. Since $M_{g} \subset N_{g}$ and $t_{\lambda} \notin N_{g}$, it follows that $t_{\lambda} \notin M_{g}$. Since $M_{g}$ is closed, there exists a compact neighborhood $W$ of $t_{\lambda}$ such that $M_{g} \cap W=\varnothing$. Without loss
of generality, we assume $W \subset A_{i}$. Now let $\rho$ be a continuous function such that $0 \% \rho(t) \quad 1$ for $t \in T, \rho\left(t_{\lambda}\right) \quad$ 1. $\rho(t) \cdots 0$ for $t \leqslant T$. and define

$$
g_{s}(t):-\rho(t) g\left(t_{0}\right) \quad(1 \quad \rho(t)) g(t)
$$

Then the function $g_{\delta}$ is in $C_{0}(T, X)$. and $g_{b} g \quad \delta$. Furthermore. we have for all $t \in T$

$$
\left|g_{\delta}(t)\right|=\rho(t)\left|g\left(t_{0}\right)\right|:(1-\rho(t)) g(t) \quad g
$$

and for $t \in T W$ the equality $g_{\delta}(t)=g(t)$. The set $T W$ is a neighborhood of $M_{u,}$. Therefore we have $M_{y_{s}} \supset M_{t r}$, and hence $0 \in P_{\mathrm{r}}\left(g_{j}\right)$. Using Lemma 8 . we obtain $P_{\mathrm{r}}\left(g_{i}\right) \subset V_{1}$. For each element $u$ in the set

$$
B_{k}:=\left\{\sum_{k \sim 1}^{l} a_{k} \epsilon_{k} c_{k} \in V_{1}: a_{k} \because 0 \text { for } \kappa=1 \ldots . k_{1}^{\prime}\right.
$$

there follows

$$
\begin{aligned}
& \left|g_{s}-u\right| \geq \mid g_{\theta}\left(t_{\lambda}\right)-u\left(t_{\lambda}\right) \\
& \\
& =x_{\lambda}^{\prime} \mid g_{\delta}\left(t_{\lambda}\right)-\sum_{k=1}^{n} a_{k} \epsilon_{k} r_{\lambda}\left(t_{\lambda}\right)_{i}^{\prime} \\
& =x_{\lambda}^{\prime}\left(g\left(t_{0}\right)\right)-\sum_{k=1}^{l} a_{k} \epsilon_{k} x_{\lambda}^{\prime} r_{i}\left(t_{\lambda}\right) \\
& \because g
\end{aligned}
$$

and consequently $B_{k} \cap P_{V}\left(g_{i}\right)==$
If the net ( $t_{\lambda}: \lambda \in A_{1}$ ) does not satisfy the conditions of the first case, then we must consider the alternative possibility.

Second case. There is a subnet $\left(t_{A}: \lambda \in A_{4}\right)$ of $\left(t,: \lambda, A_{1}\right)$ such that $x^{\prime}\left(v_{1}\left(t_{\lambda}\right)\right)=0$ for all $\lambda \in \Lambda_{4}$ and $x^{\prime} \in \delta_{U\left(t_{0}\right)}$. Let $x_{\lambda}^{\prime}$ be an arbitrary functional in $\delta_{n}^{\prime}\left(t_{0}\right) r_{1}{ }^{\left(t_{\lambda}\right)}$. Then $x_{\lambda}{ }^{\prime}$ is not in $\delta_{y\left(t_{0}\right)}$, since $X$ is strictly convex, and $v_{1}\left(t_{\lambda}\right)$ is not proportional to $g\left(t_{0}\right)$. Hence it follows that

$$
x_{\lambda}{ }^{\prime}\left(g\left(t_{0}\right)\right)<g\left(t_{0}\right)
$$

On the other hand we have, for $y^{\prime} \in \mathscr{E}_{g(t, t)}$,

$$
g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right) \| \geqslant y^{\prime}\left(g\left(t_{0}\right)\right) \cdots y^{\prime}\left(t_{1}\left(t_{\lambda}\right)\right)=g\left(t_{0}\right) .
$$

and therefore

$$
g\left(t_{0}\right) \quad g\left(t_{0}\right) \div v_{1}\left(t_{\lambda}\right)
$$

whence it follows that

$$
\begin{equation*}
g\left(t_{0}\right)+r_{1}\left(t_{4}\right) \geqslant 1 \tag{5}
\end{equation*}
$$

and $x_{\lambda}{ }^{\prime}\left(c_{1}\left(t_{\lambda}\right)\right)>0$ for each $\lambda$ in $A_{4}$.
There are signs $\epsilon_{1}:=-1$ and $\epsilon_{2}, \epsilon_{3}, \ldots, \epsilon_{1} \in\{-1,+1\}$ such that for a suitable subnet ( $t_{\lambda}: \lambda \in A_{5}$ ) the inequalities

$$
\epsilon_{1} x_{\lambda}^{\prime}\left(c_{1}\left(t_{\lambda}\right)\right)<0
$$

and

$$
\epsilon_{\kappa} x_{\lambda}^{\prime}\left(r_{k}\left(t_{\lambda}\right)\right) \leqslant 0, \quad \text { for } \quad \kappa=2,3, \ldots, k,
$$

hold. For $\delta>0$, the set

$$
\begin{gathered}
A_{\delta}:=\left\{t \in T: \mid g\left(t_{0}\right)-g(t)\|<\delta / 3,\| v_{1}(t) \ll \delta / 3\right. \\
\text { and } \left.g\left(t_{0}\right)+v_{1}(t) \|-1 \mid<\delta / 3\right\}
\end{gathered}
$$

is an open neighborhood of $t_{0}$. Hence there is $\lambda \in A_{5}$ such that $t_{\lambda} \in A_{i}$. Furthermore, there exists a compact neighborhood $W$ of $t_{\lambda}$ such that $M_{g} \cap W=\rho$ and $W \subset A_{B}$, and there is a continuous function $\rho$ such that $0 \leqslant \rho() \leqslant 1$ for $t \in T, \rho\left(t_{\lambda}\right)=1$, and $\rho(t)=0$ for $t \in T \backslash W$. The mapping

$$
g_{\delta}(t):=\rho(t) \frac{g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right)}{\left\|g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right)\right\|}+(1-\rho(t)) g(t)
$$

is in $C_{0}(T, X)$. By using (5), we obtain for $t$ in $A_{\delta}$

$$
\begin{aligned}
\mid g_{\delta}(t)-g(t)= & \left.\rho(t) \frac{g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right)}{\| g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right) \mid}-g(t) \right\rvert\, \\
= & \frac{\rho(t)}{\| g\left(t_{0}\right)-r_{1}\left(t_{\lambda}\right)} \| g\left(t_{0}\right)-g(t)+v_{1}\left(t_{\lambda}\right) \\
& +\left(1-\left\|g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right)\right\| g(t) \|\right. \\
\leqslant & \left|g\left(t_{0}\right)-g(t)\right|\left\|v _ { 1 } ( t _ { \lambda } ) \left|+\left|1-\| g\left(t_{0}\right)+v_{1}\left(t_{\lambda}\right)\right|<\delta .\right.\right.
\end{aligned}
$$

For $t$ not in $A_{\delta}$ the equality $g_{\delta}(t)=g(t)$ holds, and hence $\left\|g_{\delta}-g\right\|<\delta$. By construction, we have $\left\|g_{\delta}\right\|==1$. Since $g_{\delta}(t)=g(t)$ for $t$ in the neighborhood $T \backslash W$ of $M_{g}$, it follows that $M_{q_{\delta}} \supset M_{g}$, hence 0 is in $P_{V}\left(g_{\delta}\right)$, and, by Lemma 8, $P_{V}\left(g_{\delta}\right) \subset V_{1}$.

For each element $u$ in

$$
\left.B_{k}:=\sum_{k=1}^{k} a_{\kappa} \epsilon_{k} v_{\kappa} \in V_{1}: a_{\kappa}>0 \text { for all } \kappa\right\}
$$

there follows

$$
\begin{aligned}
& \text { g. }-\| \because \because g_{\delta}\left(t_{i}\right) \cdots u\left(t_{i}\right) \\
& x_{\lambda}\left(g_{\delta}\left(t_{\lambda}\right)-\sum_{k=1}^{i} a_{i} \epsilon_{k} r_{n}\left(t_{\lambda}\right)\right) \\
& x_{\lambda}^{\prime}\left(\frac{g\left(t_{0}\right) \div r_{1}\left(t_{\lambda}\right)}{g\left(t_{0}\right) \div t_{1}\left(t_{\lambda}\right)}\right) \quad \sum_{n=1}^{n} a_{n} \epsilon_{n} x_{\lambda}^{\prime} c_{n}\left(t_{3}\right) \quad 1 .
\end{aligned}
$$

whence $B_{V:} \cap P_{V}\left(g_{\hat{o}}\right) \cdots$
Thus in either case we have the following situation. The set $B_{i}$ is open (in $V_{1}$ ). and contains the zero element in its boundary. Since 0 is an interior point of $P_{f}(g)$ (relative to $V_{1}$ ), it follows that $P_{r}(g) \cap B_{f}$. On the other hand for each $\delta>0$ there exists a $g_{i}$ in $C_{0}(T, X)$ with:g $g_{0}<\delta$ and $P_{v}\left(g_{\partial}\right) \cap B_{V}=\therefore$. This contradicts the lower semicontinuity of $P_{V}$. Thus the theorem is proved.

Remarks. In the case $T$ compact and $X$ the real axis, Theorem 9 specializes to a result of Blatter, Morris, and Wulbert [2]. The special case of Theorem 9. when $X$ is a pre-Hilbert space, was proved by Brosowski et al. [3]. but only for locally compact spaces $T$ which have additional properties.

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